



CHARON2 X with AccurET Modular

Data Sheet



HIGH PRECISION POSITIONING STAGE

CHARON2 X

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ASME-TLMG00100303QBS0650X STANDALONE AXIS

AXIS DESIGNATION Number of controlled axes		1	
Axes name		X	
Axes name Thrust transmitter: DD (direct drive) or ID (indirect drive)		DD	
Thirdst transmitter. DD (direct drive) or 1D (indirect drive	;)		
TESTING CONDITIONS	UNIT		
Position controller		Modular 300 7/15 Arms	
Motion controller	_	UltimET	
Rated payload	kg	5	
Rated input voltage	VDC	96	
Fool point position	mm	195	
Ambient temperature	°C	22 ±1	
Isolation system	_	QuiET	
ociación dyelem			
DIMENSIONAL DATA	UNIT		
Width	mm	336	
Length	mm	1050 with handles / 984 without handles	
Height	mm	144	
Total stroke	mm	650	
Moving mass (without payload)	kg	6	
Total mass (without payload)	kg	53	
		•	
FORCE CAPABILITIES (1)	UNIT	<u> </u>	
Peak force	N	332	
Continuous force	N	130	
Standstill force	N	98	
Max. detent force(average to peak)	N	7.1	
Static friction (maximal value)	N	22	
Dynamic friction (maximal value)	N/(m/s)	60	
		•	
LOAD CAPACITIES	UNIT		
Maximum payload	kg	35	
DYNAMIC PERFORMANCE	UNIT		
Duty cycle	%	30	
Maximum speed	m/s	1	
Maximum acceleration	m/s ²	20	
Typical position stability at 2kHz	nm	±10	
		•	
ACCURACY	UNIT		
Positioning accuracy (without mapping)	μm	±12.5	
Positioning accuracy (with mapping)	μm	±1	
Bidirectional repeatability	μm	±0.3	
Horizontal straightness / radial runout	μm	±2.5	
Vertical straightness / total axial error at tool point	μm	±2	
Roll	arcsec	±3	
Pitch	arcsec	±3.5	
Yaw	arcsec	±5	
WORKING ENVIRONMENT			
Clean room compatibility (2)		ISO 2	

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	ELECTRICAL SPECIFICATIONS (1)	UNIT	
	Motor type	-	Ironcore
	Motor model	_	LMG10-030-3QB-219
	Number of phases	_	3
Kt	Force constant	N/Arms	26.6
Ku	Back EMF constant (3)	Vrms/(m/s)	16.2
Km	Motor constant	Nm/√W	16.8
R20	Electrical resistance at 20 °C (3)	Ohm	1.68
L1	Electrical inductance (3)	mH	9.02
lp	Peak current	Arms	15
lc	Continuous current	Arms	5
ls	Standstill current	Arms	3.79
ns	Standstill speed	mm/s	0.22
Um	Max. input voltage	VDC	100
Рс	Max. cont. power dissipation	W	77.6
2τр	Magnetic period	mm	32
	ENCODER CHARACTERISTICS der and signal type ut signal	UNIT -	Optical - incremental
	ut signal	-	1 Vpp
Signal period or line count Reference mark		μm	4
		-	One
Powe	er supply	V	5
	TYPICAL MOVE AND SETTLE TIMES	UNIT	
Move	e 1: 10 μm within ±100 nm window	ms	40
Move	2: 25 mm within ±100 nm window	ms	130
Move	3: 80 mm within ±100 nm window	ms	185
		•	
	GUIDING ELEMENTS		
Type			Ball bearing
	MATERIAL AND FINISH		
Base			Granite
Carria	•		Stainless steel
Carri	~J~		Claimoss steel

According to the Machinery Directive 2006/42/EC, the system presently described falls into the "partly completed machinery" category and fully complies with it as long as the system is operated according to the working conditions described in the corresponding manual. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the system is used in an improper way.

Notes: The specifications given may be mutually exclusive. Unless stated otherwise, all measurements are made within the testing conditions.

- (1) Tolerances on electrical parameters are available on request.
- (2) Under laminar flow conditions at 0.25 m/s along X axis. Measured at 230 mm from the bottom surface of the stage. Contact ETEL for more details.
- (3) Terminal to terminal.