



# **VULCANO** Platform



# VULCANO MOTION PLATFORM

#### A modular design

The Vulcano stage provides high dynamics, great bidirectional repeatability and outstanding position stability performance as well as short move and settle time due to the stiffness and symmetry of the mechanical design. This platform is equipped with a built-in vacuum suction device allowing ISO1 clean room compatibility. The stage is easily configurable and can be outfitted with different modules (Theta, ZT or Z3T) to best suit each individual application. The use of this platform is suitable for (but not limited to) Wafer Process Control applications such as Overlay Metrology, Critical Dimension and Thin film Metrology as well as other Back-end processes made on large panels / substrates.

## COMPLETE SOLUTION

#### **ETEL Forward Integration**

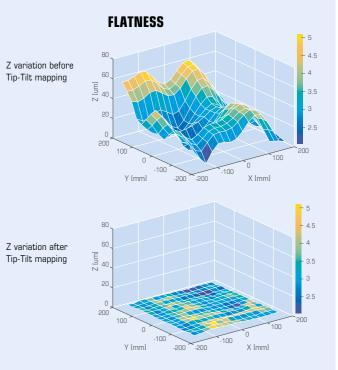
ETEL is pushing ahead with its Forward Integration Strategy. An advanced motion platforms from ETEL will include not only the advanced motion system and its associated state-of-the-art motion controllers, but can also benefit from ETEL's QuiET active isolation system. This makes ETEL the only motion system supplier able to cover such a wide scope of supply!

VULCANO XY			STANDARD MODULES	MOTION SYSTEMS PLATFORM	MOTION SYSTEM PERFORMANCE						
The Vulcano XY system i a compact and cost en mechanical bearings and h The bottom axis is con	gineered soluti nigh-end optical (	on, coupled to encoders.	RTTB ROTARY AXIS	VULCANO XYT	<ul> <li>Compact footprint</li> <li>Nanometer position</li> <li>Short move and s</li> <li>High dynamics</li> </ul>	<ul> <li>High bidirectional repeatability</li> <li>High position stability</li> <li>ISO1 clean room compatibility</li> </ul>					
The bottom axis is composed of two linear motors controlled in a gantry mode moving on three decoupled linear bearings. The upper linear motor lays on a stiff and light baseplate allowing travels up to 650 mm on a standard.							Y1-Y2	2			THETA
					Travel range 49		490 mi	190 mm 420 mm		;	367°±2°
					Maximum speed	1.5 m		s	1.5 m/s		60 rpm
					Maximum acceleration	n 25 m/		/s² 25 m/s²		1	69 rad/s²
					Position stability		±1.1 nr	nm ±0.8 nm			±1.9 nm @ R=150 mm
				The Vulcano XYT platform is made up of the	Bidir. repeatability		±350 nm		±(	D.3 arcsec	
				standard Vulcano XY outfitted with the RTTB rotary module which includes high resolution encoder	Move and settle times (25 mm within ±100 nm	150 m		s 140 ms			-
				coupled to a high-end mechanical bearing.	Maximum payload		-		-		30 kg
			Z3T <sup>#</sup> COMBINED MODULE	VULCANO XYZ3T <sup>#</sup>	<ul> <li>Compact footprint</li> <li>Nanometer position stability</li> <li>High dynamics</li> <li>Short move and settle times</li> <li>ISO1 clean room compatibility</li> <li>Tip-Tilt correction</li> <li>Double Z integration</li> <li>Built-in gravity compensator in Z</li> <li>Outstanding Z straightness</li> <li>Enhanced Z repeatability and jitter</li> <li>Ability to correct stage flatness</li> <li>Built-in vacuum supply at chuck level</li> </ul>						
			C			Y1-Y2	Х	FINE Z	TIP-TILT	COARSE Z	THETA
	Y1-Y2	Х			Travel range	490 mm 4	20 mm	±2 mm	±0.1°	15 mm	364°
Travel range	up to 650 mm	up to 650 mm			Maximum speed	1.5 m/s 1	.5 m/s	-	-	-	95.5 rpm
Maximum speed	2 m/s	2 m/s			Maximum acceleration	2.5 m/s² 2	25 m/s²		÷	-	55 rad/s²
Maximum acceleration	25 m/s <sup>2</sup>	25 m/s²		The Vulcano XYZ3T <sup>H</sup> platform is made up of the	Position stability	±0.6 nm ±	07nm	+1 9 nm	±0.0043		±0.0038
Position stability	down to ±0.7 nm			standard Vulcano XY outfitted with the Z3T <sup>H</sup> combined module. This 4 degrees of freedom	r osloon stability	10.01111 1		21.01111	arcsec		arcsec
Bidir. repeatability	±350 nm			module, provides 364° Theta rotation, double	Bidir. repeatability	±350 r	nm	±10nm	-	-	±0.35 arcsec
Move and settle times (25 mm within ±100 nm)	150 ms 140 ms			Z-axes, a coarse one for wafer loading and unloading, and a fine one for focus adjustment,	Move and settle times (25 mm within $\pm$ 100 nm)	150 ms 1	140 ms	-	-	-	-
Maximum payload	Maximum payload 40 kg			as well as a Tip-Tilt correction over ±0.1°. Maximum payload 2 kg							



#### **MOVE AND SETTLE TIME** $10 \ \mu m \pm 100 \ nm$ Tracking error [µm] 0.4 0.3 Real motion Position window 0.2 -0.1 0 . -0.1 -0.2 -0.3 -0.4 0.05 0.1 0.15 0.2 0.25 0.3 0.35 0.4 0.45 0.5 Time [s]

**TYPICAL MEASUREMENT** 







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