



# XY STACKED SYSTEM

ASME-NNNN-02-0475-0410xx

CHARON2 HD XY with AccurET Modular

Data sheet

Version 1.0

**PRELIMINARY**

**ETEL**

AXIS DESIGNATION		
Number of controlled axes		2
Axes name	X (bottom axis)	Y (top axis)
Thrust transmitter: DD (direct drive) or ID (indirect drive)	DD	DD

TESTING CONDITIONS	UNIT		
Position controller	-	Modular 300 (7/15A)	
Motion controller	-	UltimET	
Rated payload	kg	7	
Rated input voltage	VDC	300	
Tool point position	mm	246.5 above bottom surface	
Ambient temperature	°C	22 ± 1	
Isolation system	-	QuiET	

DIMENSIONAL DATA	UNIT		
Width	mm	786	
Length	mm	948	
Height	mm	226.5	
Total stroke	mm	475	410
Moving mass (without payload)	kg	26.6	6.4
Total mass (without payload)	kg	60	

FORCE CAPABILITIES (1)	UNIT		
Peak force	N	953	658
Continuous force	N	350	185
Standstill force	N	264	140
Max. detent force (average to peak)	N	26	16
Static friction (maximal value)	N	25	25
Dynamic friction (maximal value)	N/(m/s)	25	25

LOAD CAPACITIES	UNIT		
Maximum payload	kg	30	

DYNAMIC PERFORMANCE	UNIT		
Duty cycle	%	25	60
Maximum speed	m/s	2	2
Maximum acceleration	m/s <sup>2</sup>	20	20
Typical position stability at 2 kHz	nm	±40	±40

ACCURACY	UNIT		
Positioning accuracy (without mapping)	µm	±20	
Positioning accuracy (with mapping)	µm	±1	
Bidirectional repeatability	µm	±0.4	
Horizontal straightness / radial runout	µm	±3	±3.5
Vertical straightness / total axial error	µm	±2.5	±5
Orthogonality	arcsec	±15	
Roll	arcsec	±5	±10
Pitch	arcsec	±5	±25
Yaw	arcsec	±10	±10

WORKING ENVIRONMENT			
Clean room compatibility (2)	-	ISO 2	

ELECTRICAL SPECIFICATIONS (1)		UNIT	X (bottom axis)	Y (top axis)
	Motor type	-	Ironcore	Ironcore
	Motor model	-	LMS15-050-3QC	LMG10-050-3QB
	Number of phases	-	3	3
<b>Kt</b>	Force constant	N/Arms	85.3	51.2
<b>Ku</b>	Back EMF constant (3)	Vrms/(m/s)	50.9	31
<b>Km</b>	Motor constant	Nm/√W	44.3	27.3
<b>R20</b>	Electrical resistance at 20°C (3)	Ohm	2.47	2.35
<b>L1</b>	Electrical inductance (3)	mH	23.8	13.7
<b>Ip</b>	Peak current	Arms	15	15
<b>Ic</b>	Continuous current	Arms	4.2	3.71
<b>Is</b>	Standstill current	Arms	3.18	2.81
<b>ns</b>	Standstill speed	m/s	0.15	0.16
<b>Um</b>	Max. input voltage	VDC	300	300
<b>Pc</b>	Max. cont. power dissipation	W	73.5	55.9
<b>2tp</b>	Magnetic period	mm	32	32

ENCODER CHARACTERISTICS		UNIT		
	Encoder and signal type	-	Optical - incremental	Optical - incremental
	Output signal	-	1 Vpp	1 Vpp
	Signal period or line count	µm	4	4
	Reference mark	-	One	One
	Power supply	V	5	5

VACUUM CHARACTERISTICS		UNIT		
	<b>Vacuum supply for wafer chuck</b>			
	Vacuum at interface output	bar	-0.6	
	<b>Vacuum supply for axis cleanliness</b>			
	Vacuum flow	l/min	10	6

TYPICAL MOVE AND SETTLE TIMES		UNIT		
	Move 1: 10 µm within ±100 nm window	ms		40
	Move 2: 25 mm within ±100 nm window	ms		130
	Move 3: 80 mm within ±100 nm window	ms		180

GUIDING ELEMENTS				
	Type	-	Ball bearing	Ball bearing

MATERIAL AND FINISH				
	Baseplate	-	Anodized aluminum	Aluminium & silicon alloy
	Carriage	-	Aluminium & silicon alloy	Anodized aluminum

OPTIONS / ACCESSORIES / FEATURES				
	Temperature sensors	-	Yes	No

According to the Machinery Directive 2006/42/EC, the system presently described falls into the "partly completed machinery" category and fully complies with it as long as the system is operated according to the working conditions described in the corresponding manual. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the system is used in an improper way.

**Notes:** The specifications given may be mutually exclusive. Unless stated otherwise, all measurements are made within the testing conditions.

- (1) Tolerances on electrical parameters are available on request.
- (2) Under vertical laminar flow conditions at 0.5 m/s . Measured at tool point level. Contact ETEL for more details.
- (3) Terminal to terminal.