

#### AXIS DESIGNATION

Number of controlled axes	7					
Axes name	X	Y	Fine Z	Tip-Tilt	Theta	Coarse Z
Thrust transmitter: DD (direct drive) or ID (indirect drive)	DD	DD	DD	DD	DD	DD

#### TESTING CONDITIONS

	UNIT						
Position controller	-	VHP 100 (10/30 Arms)		VHP 48 (5/10 Arms)		VHP 100 (7/15 Arms)	
Motion controller	-	ULTIMET					
Rated payload	kg	2					0.25
Rated inertia	kg.m <sup>2</sup>	-	-	-	-	0.018	-
Rated input voltage	VDC	96	96	48	48	96	96
Tool point position	mm	270 mm above bottom surface					
Ambient temperature	°C	22 ± 1					
Isolation system	-	QUIET					

#### DIMENSIONAL DATA

	UNIT						
Width	mm	746					
Length	mm	844					
Height	mm	250					
Total stroke	mm or °	365	355	±2	±0.08°	364°	12
Moving mass (without payload)	kg	25.0	15.0	5	-	3	0.6
Total mass (without payload)	kg	55					
Rotor inertia (without payload)	kg.m <sup>2</sup>	-	-	-	-	0.004	-

#### FORCE / TORQUE CAPABILITIES (1)

	UNIT						
Peak force / torque	N or Nm	512	298	65.3	-	7.36	34.4
Continuous force / torque	N or Nm	130	54.3	15.7	-	0.831	11.3
Standstill force / torque	N or Nm	98	40.9	-	-	0.669	-
Max. detent force / torque (average to peak)	N or Nm	7.1	7.9	-	-	0	-
Static friction (maximal value)	N or Nm	22	22	-	-	0.2	5
Dynamic friction (maximal value)	N/(m/s) or Nm/(rad/s)	22	22	-	-	0.2	3

#### LOAD CAPACITIES

	UNIT						
Maximum axial load	N	-	-	-	-	25	4

#### DYNAMIC PERFORMANCE

	UNIT						
Duty cycle	%	18	17	-	-	6	70
Maximum speed	m/s or rad/s	1	1	0.1	-	10	0.25
Maximum acceleration	m/s <sup>2</sup> or rad/s <sup>2</sup>	10	10	3	-	180	8
Typical position stability at 2 kHz	nm or arcsec	±2	±2	±3	-	±0.025	±50

#### ACCURACY

	UNIT						
Positioning accuracy (without mapping)	µm or arcsec	±20	±20	-	-	±30	-
Positioning accuracy (with mapping)	µm	±1	±1	-	-	-	-
Unidirectional repeatability	µm	-	-	-	-	-	±10(2) / ±5(3)
Bidirectional repeatability	µm or arcsec	±0.4	±0.4	±0.03	-	±2	±15(2) / ±7.5(3)
Horizontal straightness / radial runout	µm or arcsec	±3	±3.5	-	-	±3.5	-
Vertical straightness / total axial error at tool point	µm or arcsec	±2.5	±5	-	-	±3	-
XY displacement while moving in Z (4)	µm	-	-	±0.1	-	-	±15
Orthogonality	arcsec	±15	±15	-	-	-	-
Roll	arcsec	±5	±10	-	-	-	-
Pitch	arcsec	±5	±15	-	-	-	-
Yaw	arcsec	±10	±10	-	-	-	-

#### WORKING ENVIRONMENT

Clean room compatibility (5)		ISO2					

ENCODER CHARACTERISTICS	UNIT	X	Y	Fine Z	Tip-Tilt	Theta	Coarse Z
Encoder and signal type	-	Optical Incremental					Optical absolute
Output signal	-	1 Vpp	1 Vpp	1 Vpp	1 Vpp	1 Vpp	EnDat 2.2
Signal period or line count	µm or period/turn	4	4	4	4	18'000	10
Reference mark	-	One	One	One centered in Z		One	Absolute
Power supply	V	5					

ELECTRICAL SPECIFICATIONS (1)	UNIT					
Motor type	-	Ironcore	Ironcore	Electro-Magnet	Ironless	Electro-Magnet
Motor model	-	LMG10-030-3QB	LMG05-030-3RA	EMF-14.5-058-1NA-219	SLICE0109-15	EMG012-75
Number of phases	-	3	3	3 x single-phase	3	1
<b>Kt</b> Force constant	N/Arms or Nm/Arms or N/ADC	26.6	24.6	19.6	0.646	10.7
<b>Ku</b> Back EMF constant (6)	Vrms/(m/s) or Vrms/(rad/s) or VDC/(m/s)	16.2	14.9	19.6	0.372	10.9
<b>Km</b> Motor constant	Nm/√W	16.8	13.2	8.34	0.309	6.11
<b>R20</b> Electrical resistance at 20°C (6)	Ohm	1.68	2.31	5.5	2.92	3.06
<b>L1</b> Electrical inductance (6)	mH	9.02	10.8	13.5	5.52	8.97
<b>Ip</b> Peak current	Arms	30	19.9	3.38	11.8	3.49
<b>Ic</b> Continuous current	Arms	5.00	2.26	0.8	1.33	1.05
<b>Is</b> Standstill current	Arms	3.79	1.71	-	1.01	-
<b>ns</b> Standstill speed	m/s or rad/s	0.22	0.2	-	-	-
<b>Um</b> Max. input voltage	VDC	100	100	48	100	100
<b>Pc</b> Max. cont. power dissipation	W	77.6	20.4	3.88	8.75	3.93
<b>2τp</b> Magnetic period	mm	32	32	-	-	-
<b>2p</b> Number of poles	-	-	-	-	32	-

VACUUM CHARACTERISTICS (7)	UNIT					
Vacuum supply for wafer chuck : vacuum at interface output	bar	-	-	-0.6		
Vacuum supply for axis cleanliness : vacuum flow	l/min	20	20	-	-	5 5

TYPICAL MOVE AND SETTLE TIMES	UNIT					
Move 1: 10 µm within ±100 nm	ms	50	-	-	-	-
Move 2: 25 mm within ±100 nm	ms	170	-	-	-	-
Move 3: 80 mm within ±100 nm	ms	250	-	-	-	-
Move 4: 100 µm within ±50 nm	ms	-	-	60	-	-
Move 6: 1 mm within ±50 nm	ms	-	-	100	-	-
Move 7: 10 mm within ±500 nm	ms	-	-	-	-	180
Move 8: 1° within ±40 µdeg	ms	-	-	-	-	70
Move 9: 180° within ±40 µdeg	ms	-	-	-	-	450

GUIDING ELEMENTS					
Type	Ball bearing	Ball bearing	Flexures	Ball bearing	Ball bearing

MATERIAL AND FINISH					
Baseplate	Granite	Aluminium	Anodized aluminum	-	Stainless steel
Carriage	Aluminium	Stainless steel	Anodized aluminum	Stainless steel	Stainless steel

OPTIONS / ACCESSORIES / FEATURES	UNIT					
Gravity compensation	N	-	-	Yes	-	- Yes

According to the Machinery Directive 2006/42/EC, the system presently described falls into the "partly completed machinery" category and fully complies with it as long as the system is operated according to the working conditions described in the corresponding manual. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the system is used in an improper way.

**Notes:** The specifications given may be mutually exclusive. Unless stated otherwise, all measurements are made within the testing conditions.

- (1) Tolerances on values are available upon request.
- (2) Measured at a radius of 150 mm over full stroke.
- (3) Measured at a radius of 150 mm over a limited stroke of 0 to + 3 mm.
- (4) Maximum displacement measured on a 100 µm sliding window, wherever the position on the fine Z stroke.
- (5) Measured at the chuck interface level under horizontal laminar flow at 0.4m/s without activating the Theta hard-stop.
- (6) Terminal to terminal.
- (7) Clean dry air : maximum size of particule 1 µm, maximum condensing point +3 °C, maximum concentration of oil 0.1 mg/m3.

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