



XYT STACKED SYSTEM

ASME-NNNN-03-0365-0355xx

CHARON2 HD XYT (DXR+) with AccurET VHP

Data sheet

Version 1.0

PRELIMINARY

ETEL

AXIS DESIGNATION			
Number of controlled axes	3		
Axes name	X (bottom axis)	Y (top axis)	Theta
Thrust transmitter: DD (direct drive) or ID (indirect drive)	DD	DD	DD

TESTING CONDITIONS		UNIT		
Position controller	-		VHP100 (10/30A)	VHP100 (7/15A)
Motion controller	-		UltimET	
Rated payload	kg		-	2
Rated inertia	kg.m ²		-	0.018
Rated input voltage	VDC		96	96
Tool point position	mm		246.5 above bottom surface	
Ambient temperature	°C		22 ± 1	
Isolation system	-		QuiET	

DIMENSIONAL DATA		UNIT			
Width	mm		730		
Length	mm		839		
Height	mm		226.5		
Total stroke	mm or °		365	355	Infinite
Moving mass (without payload)	kg		30.6	11.4	-
Total mass (without payload)	kg		55		
Rotor inertia (without payload)	kg.m ²		-	-	0.004

FORCE / TORQUE CAPABILITIES (1)		UNIT			
Peak force / torque	N or Nm		991	681	7.87
Continuous force / torque	N or Nm		360	193	1.74
Standstill force / torque	N or Nm		272	145	1.32
Max. detent force / torque (average to peak)	N or Nm		26	16	0
Static friction (maximal value)	N or Nm		25	25	1
Dynamic friction (maximal value)	N/(m/s) or Nm/(rad/s)		25	25	0.03

LOAD CAPACITIES		UNIT		
Maximum payload	kg		30	

DYNAMIC PERFORMANCE		UNIT			
Duty cycle	%		25	60	10
Maximum speed	m/s or rad/s		1.25	1.25	30
Maximum acceleration	m/s ² or rad/s ²		20	20	180
Typical position stability at 2 kHz	nm or arcsec		±2	±2	±0.02

ACCURACY		UNIT			
Positioning accuracy (without mapping)	µm or arcsec		±20		±30
Positioning accuracy (with mapping)	µm or arcsec		±1		±3
Unidirectional repeatability	µm or arcsec		-	-	±1
Bidirectional repeatability	µm or arcsec		±0.4		±2
Horizontal straightness / radial runout	µm		±3	±3.5	±3.5
Vertical straightness / total axial error at tool point	µm		±2.5	±5	±3
Orthogonality	arcsec		±15		-
Roll	arcsec		±5	±10	-
Pitch	arcsec		±5	±25	-
Yaw	arcsec		±10	±10	-

WORKING ENVIRONMENT		UNIT		
Clean room compatibility (2)	-		ISO 2	

ELECTRICAL SPECIFICATIONS (1)		UNIT	X (bottom axis)	Y (top axis)	Theta
Motor type	-		Ironcore	Ironcore	Toothless
Motor model	-		LMS15-050-3TC	LMG10-050-3TB	TTB0126-030-3NA-239
Number of phases	-		3	3	3
Kt Force constant	N/Arms or Nm/Arms		45.4	26.8	1.23
Ku Back EMF constant (3)	Vrms/(m/s) or Vrms/(rad/s)		27.1	16.3	0.712
Km Motor constant	Nm/√W		45.5	28.2	-
R20 Electrical resistance at 20°C (3)	Ohm		0.663	0.605	10.5
L1 Electrical inductance (3)	mH		6.74	3.77	2.65
Ip Peak current	Arms		30	30	6.9
Ic Continuous current	Arms		8.14	7.33	1.47
Is Standstill current	Arms		6.17	5.55	1.11
ns Standstill speed	m/s or rad/s		0.15	0.16	0.0016
Um Max. input voltage	VDC		100	100	100
Pc Max. cont. power dissipation	W		74	56.3	41.9
2τp Magnetic period	mm		32	32	-
2p Number of poles	-		-	-	28

ENCODER CHARACTERISTICS		UNIT			
Encoder and signal type	-		Optical - incremental	Optical - incremental	Optical - incremental
Output signal	-		1 Vpp	1 Vpp	1 Vpp
Signal period or line count	μm or period/turn		4	4	18'000
Reference mark	-		One	One	One
Power supply	V		5	5	5

VACUUM CHARACTERISTICS		UNIT			
Vacuum supply for wafer chuck					
Vacuum at interface output	bar			-0.6	
Vacuum supply for axis cleanliness					
Vacuum flow	l/min		10	6	5

TYPICAL MOVE AND SETTLE TIMES		UNIT			
Move 1: 10 μm within ±100 nm window	ms			40	-
Move 2: 25 mm within ±100 nm window	ms			130	-
Move 3: 80 mm within ±100 nm window	ms			180	-
Move 4: 1 deg within ±40 μdeg	ms		-	-	100
Move 5: 180 deg within ±40 μdeg	ms		-	-	500

GUIDING ELEMENTS					
Type	-		Ball bearing	Ball bearing	Crossed roller bearing

MATERIAL AND FINISH					
Baseplate	-		Anodized aluminum	Aluminium & silicon alloy	Aluminum alloy
Carriage	-		Aluminium & silicon alloy	Anodized aluminum	Stainless steel

OPTIONS / ACCESSORIES / FEATURES					
Temperature sensors	-		Yes	No	No

According to the Machinery Directive 2006/42/EC, the system presently described falls into the "partly completed machinery" category and fully complies with it as long as the system is operated according to the working conditions described in the corresponding manual. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the system is used in an improper way.

Notes: The specifications given may be mutually exclusive. Unless stated otherwise, all measurements are made within the testing conditions.

- (1) Tolerances on electrical parameters are available on request.
- (2) Under vertical laminar flow conditions at 0.5 m/s . Measured at tool point level. Contact ETEL for more details.
- (3) Terminal to terminal.