

AXIS DESIGNATION						
Number of controlled axes	7					
Axes name	X	Y	Fine Z	Tip-Tilt	Theta	Coarse Z
Thrust transmitter: DD (direct drive) or ID (indirect drive)	DD	DD	DD	DD	DD	DD

TESTING CONDITIONS	UNIT					
Position controller	-	Modular 300 (7/15A)		VHP 48 (5/10 Arms)		Modular 300 (7/15A)
Motion controller	-	ULTIMET				
Rated payload	kg	2				0.25
Rated inertia	kg.m ²	-	-	-	0.018	-
Rated input voltage	V _{DC}	96	96	48	48	96
Tool point position	mm	20 mm above Z3TM+ chuck interface				
Ambient temperature	°C	22 ± 1				
Isolation system	-	QUIET				

DIMENSIONAL DATA	UNIT					
Width	mm	808				
Length	mm	952				
Height	mm	250				
Total stroke	mm or °	475	410	±2	±0.08°	364°
Moving mass (without payload)	kg	27.4	14.8	5	-	3
Total mass (without payload)	kg	59.6				
Rotor inertia (without payload)	kg.m ²	-	-	-	-	0.004

FORCE / TORQUE CAPABILITIES (1)	UNIT					
Peak force / torque	N or Nm	332	254	65.3	-	7.36
Continuous force / torque	N or Nm	123	74.3	15.7	-	0.831
Standstill force / torque	N or Nm	92.9	56.1	-	-	0.669
Max. detent force / torque (average to peak)	N or Nm	7.1	7.9	-	-	0
Static friction (maximal value)	N or Nm	22	22	-	-	0.2
Dynamic friction (maximal value)	N/(m/s) or Nm/(rad/s)	22	22	-	-	0.2

LOAD CAPACITIES	UNIT					
Maximum axial load	N	-	-	-	-	25

DYNAMIC PERFORMANCE	UNIT					
Duty cycle	%	18	17	-	-	6
Maximum speed	m/s or rad/s	1	1	0.1	-	10
Maximum acceleration	m/s ² or rad/s ²	10	10	3	-	180
Typical position stability at 2kHz	nm or arcsec	±10	±10	±5	-	±0.04

ACCURACY	UNIT					
Positioning accuracy (without mapping)	µm or arcsec	±20	±20	-	-	±30
Positioning accuracy (with mapping)	µm	±1	±1	-	-	-
Unidirectional repeatability	µm	-	-	-	-	±10(2) / ±5(3)
Bidirectional repeatability	µm or arcsec	±0.4	±0.4	±0.03	-	±2
Horizontal straightness / radial runout	µm or arcsec	±3	±3.5	-	-	±3.5
Vertical straightness / total axial error at tool point	µm or arcsec	±2.5	±5	-	-	±3
XY displacement while moving in Z (4)	µm	-	-	±0.1	-	±15
Orthogonality	arcsec	±15		-	-	-
Roll	arcsec	±5	±10	-	-	-
Pitch	arcsec	±5	±15	-	-	-
Yaw	arcsec	±10	±10	-	-	-

WORKING ENVIRONMENT					
Clean room compatibility (5)	ISO2				

ENCODER CHARACTERISTICS	UNIT	X	Y	Fine Z	Tip-Tilt	Theta	Coarse Z
Encoder and signal type	-	Optical Incremental					Optical absolute
Output signal	-	1 Vpp	1 Vpp	1 Vpp	1 Vpp	1 Vpp	EnDat 2.2
Signal period or line count	µm or period/turn	4	4	4	4	18'000	10
Reference mark	-	One	One	One centered in Z		One	Absolute
Power supply	V	5					

ELECTRICAL SPECIFICATIONS (1)	UNIT	Ironcore	Ironcore	Electro-Magnet	Ironless	Electro-Magnet
Motor type	-	LMG10-030-3QB	LMG05-030-3RA	EMF-14.5-058-1NA-219	SLICE0109-015	EMG012-.075
Motor model	-					
Number of phases	-	3	3	3 x single-phase	3	1
Kt Force constant	N/Arms or Nm/Arms or N/A _{DC}	26.6	24.6	19.6	0.646	10.7
Ku Back EMF constant (6)	Vrms/(m/s) or Vrms/(rad/s) or V _{DC} /(m/s)	16.2	14.9	19.6	0.372	10.9
Km Motor constant	Nm/√W	16.8	13.2	8.34	0.309	6.11
R20 Electrical resistance at 20°C (6)	Ohm	1.68	2.31	5.5	2.92	3.06
L1 Electrical inductance (6)	mH	9.02	10.8	13.5	5.52	8.97
I_p Peak current	Arms	30	19.9	3.38	11.8	3.49
I_c Continuous current	Arms	5.00	2.26	0.8	1.33	1.05
I_s Standstill current	Arms or A _{DC}	3.79	1.71	-	1.01	-
n_s Standstill speed	mm/s	0.22	0.2	-	-	-
U_m Max. input voltage	V _{DC}	300	300	48	100	100
P_c Max. cont. power dissipation	W	77.6	48.5	3.88	8.75	3.93
2τ_p Magnetic period	mm	32	32	-	-	-
2p Number of poles	-	-	-	-	32	-

VACUUM CHARACTERISTICS (7)	UNIT						
Vacuum supply for wafer chuck : vacuum at interface output	bar	-	-	-0.6			
Vacuum supply for axis cleanliness : vacuum flow	l/min	20	20	-	-	5	5

TYPICAL MOVE AND SETTLE TIMES	UNIT						
Move 1: 10µm within ±100 nm	ms	50	-	-	-	-	
Move 2: 25mm within ±100 nm	ms	170	-	-	-	-	
Move 3: 80mm within ±100 nm	ms	250	-	-	-	-	
Move 4: 100µm within ±50 nm	ms	-	-	60	-	-	
Move 6: 1mm within ±50 nm	ms	-	-	100	-	-	
Move 7: 10mm within ±500 nm	ms	-	-	-	-	180	
Move 8: 1° within ±40 µdeg	ms	-	-	-	-	70	
Move 9: 180° within ±40 µdeg	ms	-	-	-	-	450	

GUIDING ELEMENTS						
Type	Ball bearing	Ball bearing	Flexures	Ball bearing	Ball bearing	

MATERIAL AND FINISH						
Baseplate	Granite	Aluminium	Anodized aluminium	-	Stainless steel	
Carriage	Aluminium	Stainless steel	Anodized aluminium	Stainless steel	Stainless steel	

OPTIONS / ACCESSORIES / FEATURES	UNIT						
Gravity compensation	N	-	-	Yes	-	-	Yes

According to the Machinery Directive 2006/42/EC, the system presently described falls into the "partly completed machinery" category and fully complies with it as long as the system is operated according to the working conditions described in the corresponding manual. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the system is used in an improper way.

Notes: The specifications given may be mutually exclusive. Unless stated otherwise, all measurements are made within the testing conditions.

- (1) Tolerances on electrical parameters are available on request.
- (2) Measured at a radius of 150 mm over full stroke.
- (3) Measured at a radius of 150 mm over a limited stroke of 0 to + 3 mm.
- (4) Maximum displacement measured on a 100 µm sliding window, wherever the position on the fine Z stroke.
- (5) Measured at the chuck interface level under horizontal laminar flow at 0.4m/s without activating the Theta hard-stop.
- (6) Terminal to terminal.
- (7) Clean dry air : maximum size of particule 1 µm, maximum condensing point +3 °C, maximum concentration of oil 0.1 mg/m3.

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