Encoder cable, length 5 m
Bending radius min., fixed configuration: 8 mm
D-sub connector, 3-row, with locking screws, male, 15-pin.
Output signal: 1 Vpp

Sensor cable, length 5 m
See note B

Power cable, length 5 m
See note B

<table>
<thead>
<tr>
<th>Power supply</th>
<th>Incremental signals</th>
<th>Other</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pin</td>
<td>4 5 14 7 13 15 8 1 2 9 10 11 12</td>
<td></td>
</tr>
<tr>
<td>1Vpp</td>
<td>Up OV</td>
<td></td>
</tr>
</tbody>
</table>

Function

Encoder supply +5 VDC
Encoder supply 0 V
Sine + signal
Sine - signal
Cosine + signal
Cosine - signal
Index + signal
Index - signal

Note A: Dimensions and tolerances are defined in the interface drawing of the TMB+0291-### motor.

Note B: Connection and bending radius are defined in the interface drawing of the TMB+0291-### motor with PT 1000 sensor.