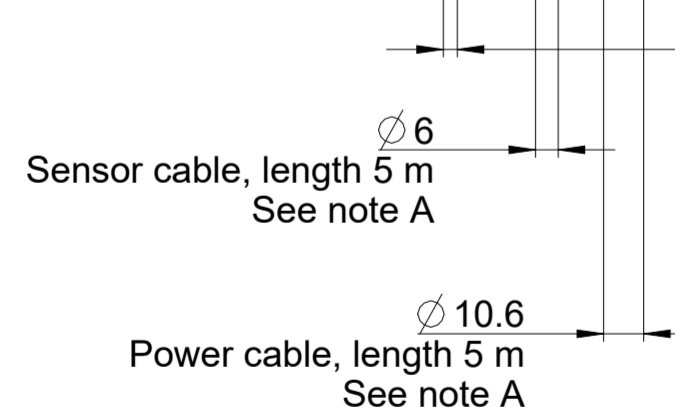
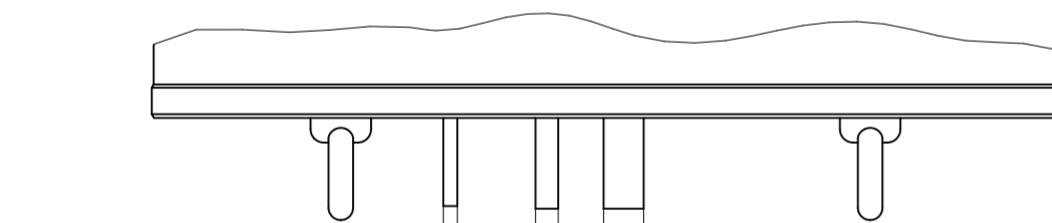
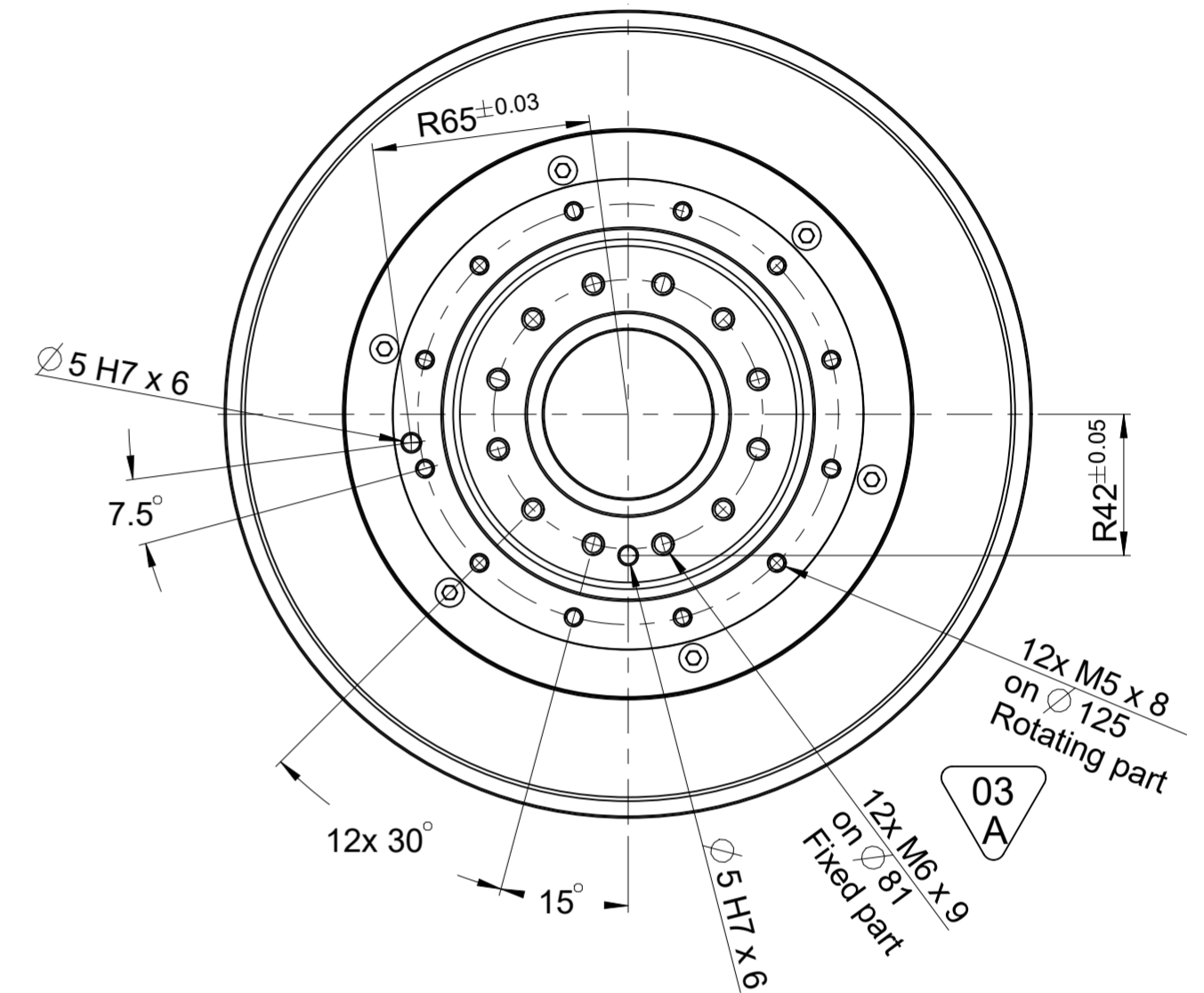
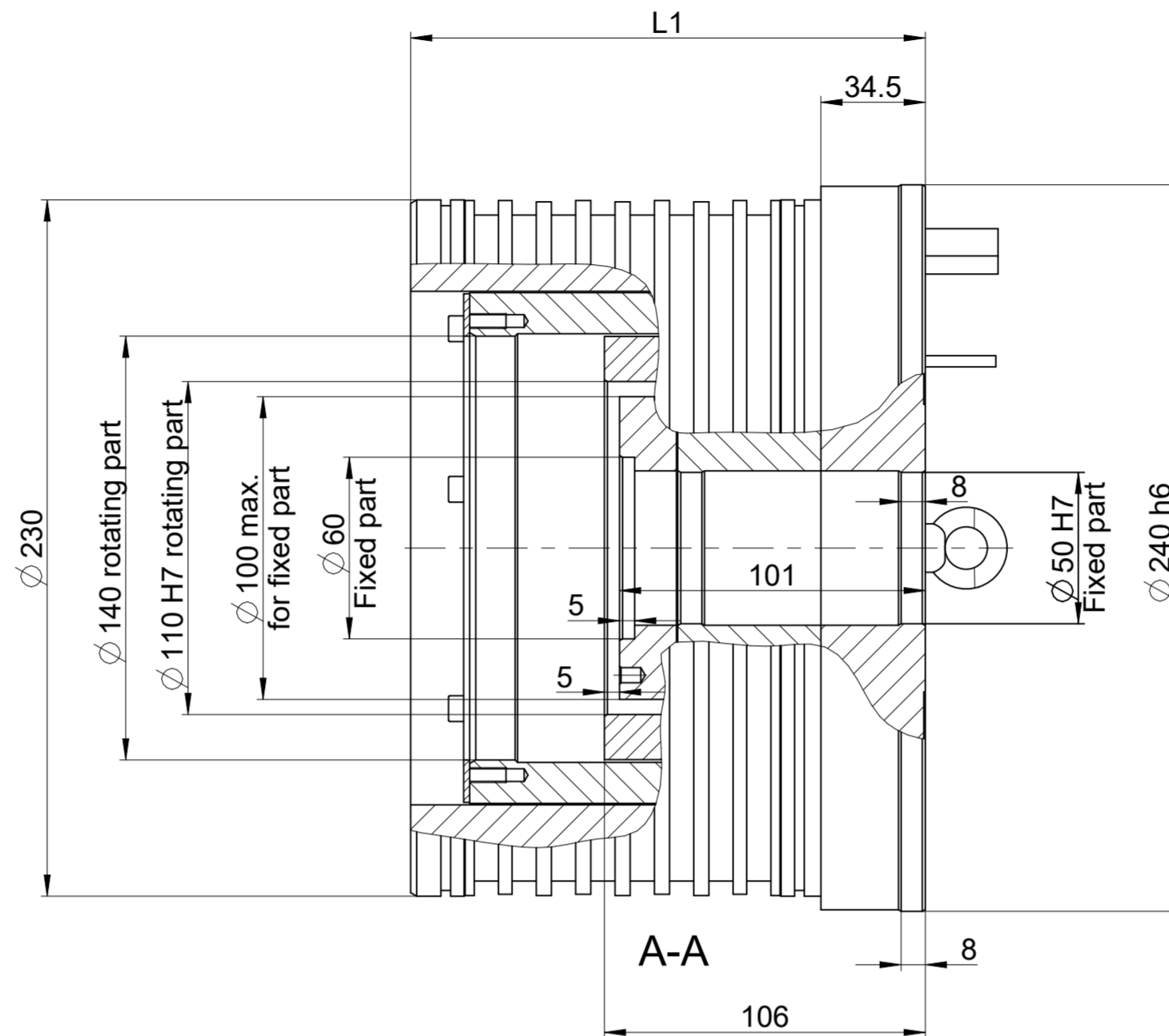
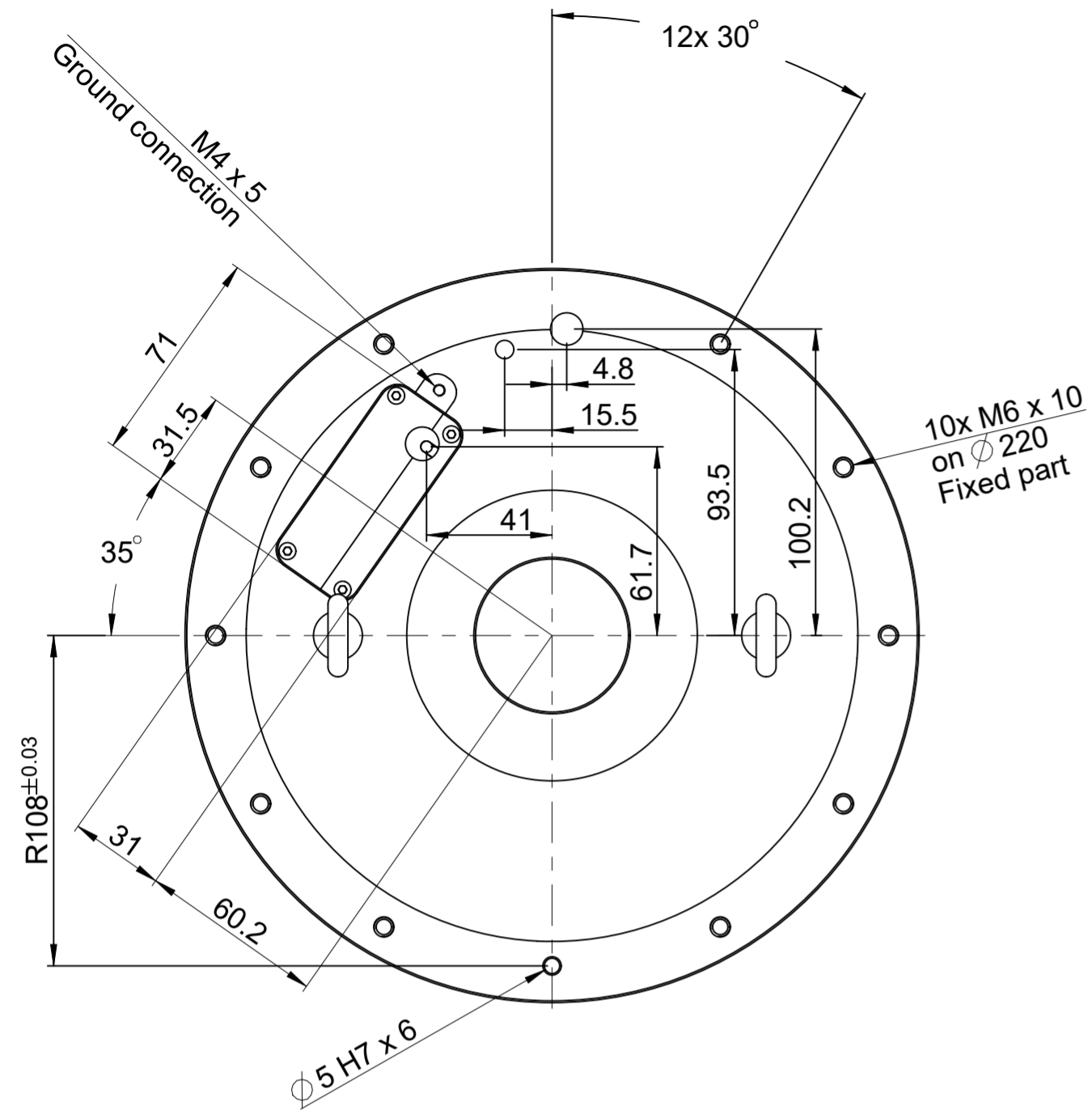
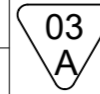
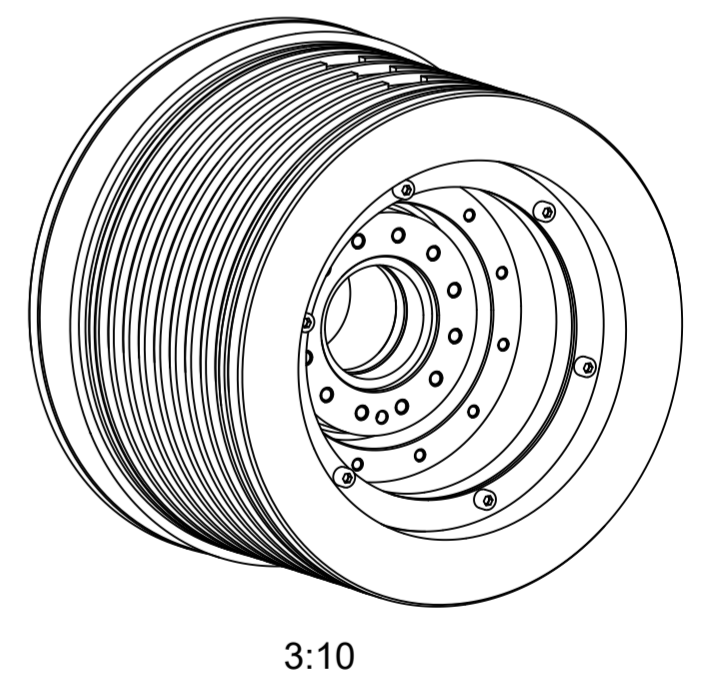
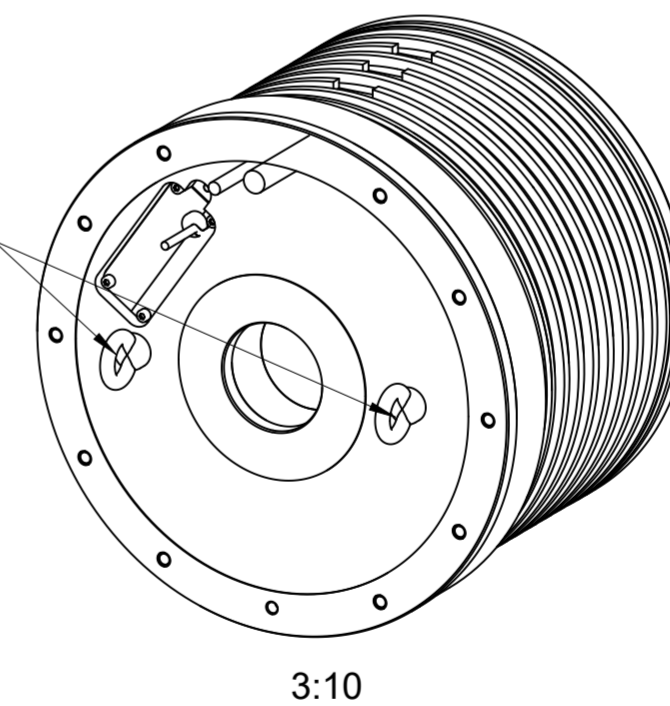


Axis	L1
RTMB+210-070	140
RTMB+210-100	170



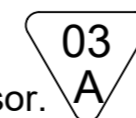
Pin	Power supply		Incrementals signals					Other							
	4	5	14	7	13	6	15	8	1	2	3	9	10	11	12
1Vpp	Up	0V	A+	A-	B+	B-	R+	R-	/	/	/	/	/	/	/
Function	Encoder supply +5VDC	Encoder supply 0V	Sine + signal	Sine - signal	Cosine + signal	Cosine - signal	Index + signal	Index - signal							

2x lifting eye bolts DIN 580 - M6
Included in delivery.



Note A: Dimensions and tolerances are defined in the interface drawing of the TMB+0210-### motor.

Note B: Connection and bending radius are defined in the interface drawing of the TMB+0210-### motor with PT 1000 sensor.



Text: Note modified		ID number: 1313248-##
Change No. C134337-05		Released: 03-Nov-21
		Tolerances as per ISO 8015 : 2011 Tolérances selon ISO 8015 : 2011 Dimensions without tolerance ± 0,5 Dimensions sans tolérances ± 0,5
Rotary axis Rtmb+210 without cooling jacket Axe rotatif Rtmb+210 without cooling jacket Mating Dimensions / Cotes d'encombrement		The reproduction, distribution and utilization of this document as well as the communication of its contents to others without express authorization is prohibited. Offenders will be held liable for the payment of damages. All rights reserved in the event of the grant of a patent, utility model or design. (ISO 16016)
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