

DynXRotary Series

Data sheet

Version 5.0





PRECISION POSITIONING STAGE ROTARY SERIES



Mm (in) mm (in) mm (in) mm (in) kg (lbs) kg.m² UNIT Nm Nm Nm	VALUES 155 (6.10) 159 (6.25) 53.5 (2.10) Ø 58 (Ø 2.28) 3.8 (8.37) 3.49 E-3 VALUES 7.87)
mm (in) mm (in) mm (in) kg (lbs) kg.m² UNIT Nm Nm	159 (6.25) 53.5 (2.10) Ø 58 (Ø 2.28 3.8 (8.37) 3.49 E-3)
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kg (lbs) kg.m ² UNIT Nm Nm	3.8 (8.37) 3.49 E-3 VALUES 7.87	
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UNIT -	VALUES 7.87	
Nm Nm	7.87	
Nm		
	474	
Nm	1.74	
	1.32	
Nm	0.55	
Nm/(rad/s)	7.3 E-3	
UNIT	VALUES	
kg (lbs)	30 (66.13)	
kg (lbs)	30 (66.13)	
UNIT	VALUES	
X10.000		
arcsec	± 0.2	
UNIT	TYPICAL VALUES	
arcsec	± 30	
arcsec	± 3	
arcsec	± 1	
arcsec	± 2	
μm	0.5	
μm	± 3.5	
μm	20	
arcsec	± 5	
UNIT	TTB0126-030-3I	NA
Nm/Arms	1.23	
Vrms/(rad/s)	0.712	
Ohm	10.5	
mH	2.65	
Arms	6.90	
Arms	1.47	
Arms	1.11	
VDC	300	
W	41.9	
-	28	
rpm	0.016	
	kg (lbs) kg (lbs) kg (lbs) UNIT rpm rad/s² arcsec UNIT arcsec arcsec arcsec arcsec µm µm µm arcsec UNIT Nm/Arms Vrms/(rad/s) Ohm mH Arms Arms Arms Arms VDC W -	kg (lbs) kg (lbs) kg (lbs) UNIT VALUES TPM rad/s² arcsec UNIT TYPICAL VALUES TYPICAL VALUES TYPICAL VALUES TYPICAL VALUES UNIT TYPICAL VALUES ### ### ### ### ### ### ###

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Ball bearing, 4 contact points

Low

Туре

Preload

ENCODER CHARACTERISTICS	
Encoder type	Non-contact, optical, metal disc
Signal type	Incremental
Output signal	1 Vpp or TTL
Number of lines of the grating disk	18'000

WORKING ENVIRONMENT	
Clean room compatibility (12)	ISO 5 (referred to ISO 14644-1 standard)
	Class 100 (referred to US Fed Std 209E)
IP protection grade (13)	IP40

MATERIALS AND FINISH	
Base	Aluminum / Black anodized
Shaft	Stainless steel

OPTIONS					
TTL encoder output signal (14)	Interpolation factor	5x	10x	50x	100x
	Max. speed [rpm] (15)	400	400	111	55
Limited stroke	< 360°	From 29° to 344° by step of 45°			
	> 360°		39	4°	
Air purge			Bidirectional pr	neumatic fitting	

ACCESSORIES	
ACCESSORIES	
	Extension cables

The DynX Rotary Series proposed by ETEL are fully compliant with the Machinery Directive 2006/42/EC as long as the system is used under the working conditions described in the DynX Hanbook. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the stage is used in an improper way.

Notes: The specifications given may be mutually exclusive.

- (1) Without limited stroke.
- (2) Tolerances: refer to the DynX Hanbook.
- (3) Coils at 80 °C, ambiant temperature at 20 °C and additional surface of 0.05 m² fixed to the base and 0.017 m² to the rotor.
- (4) Indicative load capacity with a payload centered on the stage. Please contact ETEL for any other case.
- (5) Indicative load capacity with the stage is the horizontal position, with a payload centered on the carriage and the center of gravity 20 mm above the interface surface of the carriage.
- (6) Recommended value. Please contact ETEL in case of greater requirements.
- (7) With an AccurET modular 300, at encoder level.
- (8) Values measured on a precision mounting surface (typical flatness 15 µm).
- (9) All mounting screws used. Specifications measured with an AccurET modular 300. The typical ambient temperature during the measurements is 22°C.
- (10) Value measured 17.7 mm above the interface surface of the carriage.
- (11) Terminal to terminal.
- (12) ISO 4 (class 10) on request.
- (13) Please contact ETEL for more stringent needs.
- (14) With TTL encoder cable adaptor.
- (15) For an input frequency of 10 MHz on an AccurET modular 300 position controller (input frequency is controller dependent). Limited by the interpolation chip.

