Optional temperature sensor configurations

Type 1
- White
- Brown

Type 2
- White
- Brown
- Green
- Yellow

Type 6
- White
- Brown
- Green
- Yellow

<table>
<thead>
<tr>
<th>Type 1</th>
<th>Type 2</th>
<th>Type 6</th>
</tr>
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<tbody>
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</tbody>
</table>

Direction of gravity

1 max.

(For customer's interface on the whole length and both sides of the lamination stack)

Optional Hall effect sensors

Hx M3x3.5

Identification label

Optional shielded temperature sensor cable 4x0.25 mm² (Ø 5.3)

Minimum static bending radius: 4x cable Ø

Restrained conditions for the flatness B1: the surface indicated as datum Z is fixed on a ENAW-6082 aluminium plate, thickness 25mm with H bolts M3x30 ISO 4762 quality A2-70 tightened to a torque of 1.26 Nm

ISO 10579-NR

Ironcore linear motor LMS##-###-3##-H##

Matière: Scale Format

RoHS 1:1 A2 Moteur linéaire avec fer LMS##-###-3##-H##

Dimensions in mm / Cotes en mm Mating Dimensions / Cotes d'encombrement

Arêtes de formes selon ISO 13715

Tolérances générales ISO 2768-mK

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Shielded power cable 4x0.75 mm²

Minimum static bending radius: 4x cable Ø

Optional temperature sensor configurations

7:10

Identification label

Optional shielded temperature sensor cable 4x0.25 mm²

Minimum static bending radius: 4x cable Ø

Restricted conditions for the flatness B1: the surface indicated as datum Z is fixed on a ENAW-6082 aluminium plate, thickness 25mm with H bolts M3x30 ISO 4762 quality A2-70 tightened to a torque of 1.26 Nm

ISO 10579-NR

Ironcore linear motor LMS##-###-3##-H##

Matière: Scale Format

RoHS 1:1 A2 Moteur linéaire avec fer LMS##-###-3##-H##

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Matière: Scale Format

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